

## **AMENDMENTS TO THE CLAIMS**

This listing of claims will replace all prior versions, and listings, of claims in the application:

### **Listing of Claims**

1. (Original) An arc welding robot comprising:

a robot main body including a welding torch and a wire feeder for feeding welding wire to said welding torch, said wire feeder including a sensor and a driving motor;

a robot controller for controlling said robot main body; and

a welding power supply arranged inside said robot controller, said welding power supply controlling said wire feeder and a welding power,

wherein a robot main body driving power cable and a robot control cable are connected between said robot controller and said robot main body and

wherein a sensor cable of said wire feeder, a gas valve control cable for a shield gas supplied to said welding torch and a welding voltage feedback cable are accommodated in said robot main body driving power cable.

2. (Currently amended) An arc welding robot comprising:

a robot main body including a welding torch and a wire feeder for feeding welding wire to said welding torch, said wire feeder including a sensor and a driving motor;

a robot controller for controlling said robot main body; and

a welding power supply arranged inside said robot controller, said welding power supply controlling said wire feeder and a welding power,

wherein a robot main body driving power cable, a robot control cable and a sensor cable are connected between said robot controller and said robot main body [[and]],

wherein a sensor cable of said wire feeder, a gas valve control cable for a shield gas supplied to said welding torch and a welding voltage feedback cable are accommodated in the sensor cable connected between the robot controller and the robot main body, and

wherein said sensor cable is accommodated in said robot main body driving power cable.

3. (Canceled)

4. (Original) An arc welding robot comprising:

a robot main body including a welding torch and a wire feeder for feeding welding wire to said welding torch, said wire feeder including a sensor and a driving motor,

a robot controller for controlling said robot main body; and

a welding power supply arranged inside said robot controller, said welding power supply controlling said wire feeder and a welding power,

wherein a robot main body driving power cable, a robot control cable and a sensor cable are connected between said robot controller and said robot main body and

wherein a sensor cable of said wire feeder, a gas valve control cable for a shield gas supplied to said welding torch and a welding voltage feedback cable are accommodated in said robot main body driving power cable and in said sensor cable in a dispersed fashion.